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robot can move from point A to point B in three main ways. 1.
PTP - Point-to-Point - Motion along the quickest path to an end
point. This motion requires the programmer to "teach" one point.
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that was a working example. look at the message you wish to monitor and use the KSS number. for example KSS00020 is an emergency stop and KSS00203 is General Motion Enable

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This documentation is based on a KRC4 controller. The KRC4 robot controller runs the Microsoft Embedded Windows 7 operating system. Previous controllers, such as KRC2, run Windows 95. The robot teach pendant shows an "HMI" which is a program that KUKA developed to run on Windows and it is the interface that the robot user must use to manipulate the robot.

KUKA robots - RoboDK Documentation

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The Kuka KUKA KRC4 CK KCP4 VKRC4 teach pendant membrane keypad, LCD Display and protective case shell are Kuka SmartsPAD Controller repair, make your kuku krc4 controller normal operation The front view of kuka krc4 controller Function The smartPAD krc4 is ... Kuka Robot Programming Manual - ads.baa.uk.com 'Kuka Programming Manual ...

[DOC] Kuka Operation Manual - Temple University

On the KRC4 side (in WoV) you need to map standard I/O. On the PLC side, one need to map standard I/O. If using safety over some ethernet network (CipSafety, ProfiSafe, FSoE), no mapping is needed in WoV as this Safety IO block is already defined and mapped as described in SafeOperation manual.

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